EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	3	("700".clas. "706".clas. "318".clas.) and (Fujibayashi near Kentaro).in. and virtual and (@ad<"20030212" @rlad<"20030212" @prad<"20030212")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:31
L2	4	(Fujibayashi near Kentaro).in. and virtual and (@ad<"20030212" @rlad<"20030212" @prad<"20030212")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:30
L3	5	(location position) near2 control$4 and (location position) near2 virtual and (servomotor servo-motor) and (screen display user adj interface UI GUI) with virtual and (driv$4 control$4) near (axis axes)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:33
L4	1	((location position) near control$4 near (axes axis) and (location position) near virtual near (axes axis)).clm.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:34
L5	0	("700".clas. "706".clas. "318".clas.) and virtual and (@ad<"20030212" @rlad<"20030212" @prad<"20030212") and (location position) near2 control$4 and (location position) near2 virtual and (servomotor servo-motor) and (screen display user adj interface UI GUI) with virtual and (driv$4 control$4) near (axis axes)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:36
L6	5	virtual and (@ad<"20030212" @rlad<"20030212" @prad<"20030212") and (location position) near2 control$4 and (location position) near2 virtual and (servomotor servo-motor) and (screen display user adj interface UI GUI) with virtual and (driv$4 control$4) near (axis axes)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:36
S2	2	"20040158335"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 12:23

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S11	3	(location position) near control$4 near (axes axis) and (location position) near virtual near (axes axis)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:10
S12	20	(location position) near control$4 and (location position) near virtual and (servomotor servo-motor)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 12:39
S13	57	(location position) near2 control$4 and (location position) near2 virtual and (servomotor servo-motor)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:12
S14	21	(location position) near2 control$4 and (location position) near2 virtual and (servomotor servo-motor) and (screen display user adj interface UI GUI) same virtual	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 12:53
S15	19	(location position) near2 control$4 and (location position) near2 virtual and (servomotor servo-motor) and (screen display user adj interface UI GUI) with virtual	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:03
S16	5	(location position) near2 control$4 and (location position) near2 virtual and (servomotor servo-motor) and (screen display user adj interface UI GUI) with virtual and (driv$4 control$4) near (axis axes)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:05
S17	1	((location position) near2 control$4 and (location position) near2 virtual and (servomotor servo-motor) and (screen display user adj interface UI GUI) with virtual).clm.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:03
S18	1	((location position) near2 control$4 and (location position) near2 virtual and (servomotor servo-motor) and (screen display user adj interface UI GUI) and virtual).clm.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:03
S19	1	((location position) near2 control$4 and (location position) near2 virtual and (servomotor servo-motor) and virtual and (driv$4 control$4) and (axis axes)).clm.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:07

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S20	1	((location position) near2 control$4 and (location position) near5 virtual and (servomotor servo-motor) and virtual and (driv$4 control$4) and (axis axes)).clm.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:07
S21	1	((location position) near2 control$4 and (location position) with virtual and (servomotor servo-motor) and virtual and (driv$4 control$4) and (axis axes)).clm.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:09
S22	1	((location position) near control$4 near (axes axis) and (location position) near virtual near (axes axis)).clm.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:10
S23	16	("700".clas. "706".clas. "318".clas.) and (location position) near2 control$4 and (location position) near2 virtual and (servomotor servo-motor)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:15
S24	136095	("700".clas. "706".clas. "318".clas.)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:15
S25	157	("700".clas. "706".clas. "318".clas.) and Fujibayashi.in.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:15
S26	157	("700".clas. "706".clas. "318".clas.) and (Fujibayashi near Kentaro).in.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:21
S27	4	("700".clas. "706".clas. "318".clas.) and (Fujibayashi near Kentaro).in. and virtual	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/24 13:28

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L8	1	((location position) near control$4 near (axes axis) and (location position) near virtual near (axes axis)).clm.	US-PGPUB	OR	ON	2008/01/24 13:47

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... [0048] As explained above, according to the present invention, feedback track data of a single **control axis** and a **virtual axis** orthogonal with the single ...
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C Morita, M Okada, N Takaki - US Patent 6,037,738, 2000 - Google Patents
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... [0022] Based on an NC program or PMC axis **control** (**axis** control by ... is also provided with means B2 for calculating the position of a **virtual axis** that moves at ...
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K Code, JK Weinhofer, JS Baker, KR Harris, VP ... - freepatentsonline.com
... to another axis block based on the position information from the **virtual axis**. ... In this case, position information for the motion **control axis** controlled by the ...
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System level data flow programming interface for a multi-axis industrial control system - all 3 versions »
JK Weinhofer - US Patent 6,442,442, 2002 - Google Patents
... The use of **virtual axes** in these systems provides ... first motion **control axis** and the second motion **control axis**. ... The first and second motion **control axes** may be ...
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Output cam system and method - all 4 versions »
JK Weinhofer, JS Baker, KR Harris - US Patent 7,099,719, 2006 - Google Patents
... In accordance with a first preferred embodiment, a control method comprises monitoring a position of a motion **control axis** and controlling an output device ...
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3D Microengineering via Laser Direct-Write Processing Approaches
H HELVAJIAN - Direct-Write Technologies for Rapid Prototyping Applications ..., 2002 - books.google.com
... sequence and may actually use inverse-kinematics features (" **virtual axis**") to get ... laser-induced forward transfer, MAPLE DW) additional **control axes** will also ...

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... produced. A virtual target value for moving a virtual controlled object as a **virtual axis** based on the reality axis is also produced. ...
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